Ordinary Differential Equations and Introduction to Dynamical Systems

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Overview

- Single Species Systems
 - Solving for Equilibria
 - Evaluating Stability of Equilibria Graphically
- Two Species Systems
 - Lotka-Volterra Predator-Prey
 - Evaluating Stability of Equilibria
- Examples from Epidemiology

Single Species Systems

- Exponential Growth
- Logistic Growth
- Other Equations





Logistic Growth

$$\frac{dN}{dt} = rN\left(1 - \frac{N}{K}\right)$$
What do you think the solutions of this will look like?

Recall exponential growth was

$$\frac{dN}{dt} = rN$$

Equilibria $\frac{dN}{dt} = rN\left(1-\frac{N}{K}\right)$ dN- = 0dt $rN^*\left(1-\frac{N^*}{K}\right) = 0$ $N^* = 0 \ or \ N^* = K$

Stability of EquilibriaFirst evaluate the stability of
$$N^* = 0$$
.Near $N^* = 0$, $\frac{dN}{dt} \approx rN$ So as N increase, $\frac{dN}{dt}$ grows exponentially.Therefore, $N^* = 0$ is an unstable equilibrium.

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Stability of Equilibria
What do you think will happen near
$$N^* = K$$
?
$$\frac{dN}{dt} = rN\left(1 - \frac{N}{K}\right)$$

Stability near K
If N is just slightly above K,

$$\frac{dN}{dt} = rN\left(1 - \frac{N}{K}\right) < 0$$
but if N is just slightly below K,

$$\frac{dN}{dt} = rN\left(1 - \frac{N}{K}\right) > 0$$
Therefore, $N^* = K$ is stable.







Interacting Populations
 Predator-prey models
 Competition
 Mutualism

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Classic Predator-Prey Lotka-Volterra Predator-Prey Model $\frac{dN}{dt} = rN - cNP$ $\frac{dP}{dt} = bNP - mP$

Classic Predator-Prey

Lotka-Volterra Predator-Prey Model

- Historical interest
- Mass-action term
- Bad mathematical model
- Structurally unstable



Interacting Populations More Realistic Predator-prey models $\frac{dN}{dt} = rN\left(1-\frac{N}{K}\right) - P\left(\frac{A}{N+B}\right)$ $\frac{dP}{dt} = eP\left(\frac{A}{N+B}\right) - dP$

Another More Realistic Predator-prey models

$$\frac{dN}{dt} = rN\left(1-\frac{N}{K}\right) - P\left(\frac{AN}{N^2+B^2}\right)$$
$$\frac{dP}{dt} = eP\left(\frac{AN}{N^2+B^2}\right) - dP$$

Competition

 $\frac{dN_1}{dt} = r_1 N_1 \left(1 - \frac{N_1}{K_1} - b_{12} \frac{N_2}{K_1} \right)$ $\frac{dN_2}{dt} = r_2 N_2 \left(1 - \frac{N_2}{K_2} - b_{21} \frac{N_1}{K_2} \right)$

Mutualism

 $\frac{dN_1}{dt} = r_1 N_1 \left(1 - \frac{N_1}{K_1} + b_{12} \frac{N_2}{K_1} \right)$ $\frac{dN_2}{dt} = r_2 N_2 \left(1 - \frac{N_2}{K_2} + b_{21} \frac{N_1}{K_2} \right)$

- To analyze these types of models
 - Nondimensionalize the system
 - reduce the number of parameters
 - simplfy the system
 - Solve for equilibria
 - Analyze stability of equilibria
 - Translate back to determine biological significance

Phase-Plane Techniques

- Some defintions of stability
 - Stable if start small distance from equilibrium, remain small distance as $t \to \infty$
 - Lyapunov stable
 - locally stable
 - Asymptotically stable if start small distance from equilibrium, distance from equilibrium approaches zero as $t \to \infty$
 - locally asymptotically stable

Phase-Plane Techniques

- Linearization
- Bendixson-Dulac negative criterion
- Hopf bifurcation theorem
- Poincaré-Bendixson theorem
- Routh-Hurwitz Conditions

Given:

- dNF(N, P)dtdPdt
 - G(N, P)

Linearization Solve: $F(N^*, P^*) = 0$ $G(N^*, P^*) = 0$ to find the equilibria, (N^*, P^*) . Let: $x(t) = N(t) - N^*$ $\overline{y}(t) = P(t) - P^*$

Then linearize about the equilibrium:

 \dot{x}

 \dot{y}

$$\frac{dx}{dt} = \frac{\partial F}{\partial N}\Big|_{(N^*,P^*)} x + \frac{\partial F}{\partial P}\Big|_{(N^*,P^*)} y$$
$$\frac{dy}{dt} = \frac{\partial G}{\partial N}\Big|_{(N^*,P^*)} x + \frac{\partial F}{\partial P}\Big|_{(N^*,P^*)} y$$

Or:

$$= \left(\begin{array}{cc} a_{11} & a_{12} \\ a_{21} & a_{22} \end{array}\right) \left(\begin{array}{c} x \\ y \end{array}\right)$$

Let:

$$J = \left(\begin{array}{cc} a_{11} & a_{12} \\ a_{21} & a_{22} \end{array} \right)$$

Where J is known as the Jacobian matrix or the community matrix.

We now look for solutions of the form:

$$\begin{array}{rcl} x(t) &=& x_0 e^{\lambda t} \\ & & & \\ \end{array}$$

$$y(t) = y_0 e^{\prime}$$

or

Substitute this back into the equations to obtain:

 $\lambda x_0 = a_{11}x_0 + a_{12}y_0$ $\lambda y_0 = a_{21}x_0 + a_{22}y_0$

$$\left(egin{array}{ccc} a_{11}-\lambda & a_{12} \\ a_{21} & a_{22}-\lambda \end{array}
ight) \left(egin{array}{ccc} x_0 \\ y_0 \end{array}
ight) =$$

 $\left(\right)$

From this, we obtain the characteristic equation

 $\lambda^2 - (a_{11} + a_{22})\lambda + (a_{11}a_{22} - a_{12}a_{21}) = 0$

Solving for the two roots of λ will determine the stability of the system.

- If both roots of λ are real and negative, the equilibrium is a stable node.
- If both roots of λ are real and positive, the equilibrium is an unstable node.
- If the roots of λ are real and of opposite signs, the equilibrium is a saddle point.

- If the roots of λ are complex with negative real parts, the equilibrium is a stable focus.
- If the roots of λ are complex with positive real parts, the equilibrium is an unstable focus.
- If the roots of λ are purely complex, the equilibrium of the linearized system is a center, but the original nonlinear system will have a center or a stable or unstable focus depending upon the exact nature of the nonlinear terms.

Routh-Hurwitz conditions

Routh-Hurwitz conditions give the necessary and

sufficient conditions for all roots of the

characteristic polynomial to have negative real roots thus implying asymptotic stability.

$$p = TrJ = a_{11} + a_{22} < 0$$

$$q = detJ = a_{11}a_{22} - a_{12}a_{21} > 0$$



Bendixson negative criterion Bendixson's negative criterion $\frac{dx}{dt}$ Consider the dynamical system, $F(x,y), \frac{dy}{dt} = G(x,y),$ where F and G are continuously differentiable functions on some simply connected domain $D \subset \Re^2$. If $\nabla \cdot (F, G) = \frac{\partial F}{\partial r} + \frac{\partial G}{\partial u}$ is of one sign in D, there cannot be a closed orbit contained within D.

Bendixson-Dulac negative criterion Additionally, we have the Bendixson's-Dulac's negative criterion. Let B be a smooth function on $D \subset \Re^2$ (with above assumptions). If $\nabla \cdot (BF, BG) = \frac{\partial BF}{\partial x} + \frac{\partial BG}{\partial y}$ is of one sign in D, there cannot be a closed orbit contained within D.

Other theorems

- The Hopf bifurcation theorem gives conditions necessary for the existence of real periodic solutions of a real system of ordinary differential equations.
- Poincaré-Bendixson theorem can also be used to prove the existence of periodic orbits.

Examples from Epidemiology Divide population up into distinct classes S = Susceptibles I = Infectives R = Recovered

Classes used depend on disease dynamics



SIR Model - constant population

$$\frac{dS}{dt} = \mu (S + I + R) - \alpha SI - \mu S$$

$$\frac{dI}{dt} = \alpha SI - \beta I - \mu I$$

$$\frac{dR}{dt} = \beta I - \mu R$$

$$N = S + I + R$$

$$S(0) = S_0, I(0) = I_0, R(0) = 0.$$
 All parameters are assumed to be positive.

Questions for Epidemic Models

Given all parameters and initial conditions

- Does the infection spread or die out?
- If it does spread, how does it develop with time?
- When will it start to decline?

Equilibria

Note: Since N is a constant, we can solve for only S and I, then if we need R, we can calculate it easily.

$$\frac{dS}{dt} = \mu N - \alpha SI - \mu S = 0$$
$$\frac{dI}{dt} = \alpha SI - \beta I - \mu I = 0$$



Gives two equilibria:

$$S^* = N \quad , \quad I^* = 0$$
$$S^* = \frac{\beta + \mu}{\alpha} \quad , \quad I^* = \frac{\mu \left(\alpha N - \beta - \mu\right)}{\alpha \left(\beta + \mu\right)}$$

$$F(S,I) = \mu N - \alpha SI - \mu S$$
$$G(S,I) = \alpha SI - \beta I - \mu I$$

Stability	
Then	
	$\frac{\partial F}{\partial S} = -\alpha I - \mu$ $\frac{\partial F}{\partial I} = -\alpha S$ $\frac{\partial G}{\partial S} = \alpha I$
	$\frac{\partial G}{\partial I} = \alpha S - \beta - \mu$

First, let's evaluate the stability of $S^* = N$, $I^* = 0$ The elements of the Jacobian evaluated at this equilibrium are:

$$a_{11} = -\mu$$

$$a_{12} = -\alpha N$$

$$a_{21} = 0$$

$$a_{22} = \alpha N - \beta - \mu$$

Applying the Routh-Hurwitz conditions:

$$a_{11} + a_{22} = -\beta - 2\mu$$

$$a_{11}a_{22} - a_{12}a_{21} = \mu (\beta + \mu - \alpha N)$$

Clearly, $-\beta - 2\mu < 0$ However, $\mu (\beta + \mu - \alpha N) > 0$ only if $\alpha N < \beta + \mu$ Therefore, $S^* = N, I^* = 0$ is asymptotically stable if $\alpha N < \beta + \mu$



- Now, let's evaluate the stability of
 - $S^* = \frac{\beta + \mu}{\alpha}, I^* = \frac{\mu(\alpha N \beta \mu)}{\alpha(\beta + \mu)}$
- The elements of the Jacobian evaluated at this equilibrium are:

$$a_{11} = -\mu - \frac{\mu \left(\alpha N - \beta - \mu\right)}{\beta + \mu}$$

$$a_{12} = -\beta - \mu$$
$$a_{21} = \frac{\mu (\alpha N - \beta - \mu)}{\beta + \mu}$$

 $a_{22} = 0$

Applying the Routh-Hurwitz conditions:

$$a_{11} + a_{22} = -\mu - \frac{\mu (\alpha N - \beta - \mu)}{\beta + \mu}$$
$$a_{11}a_{22} - a_{12}a_{21} = (\beta + \mu) \left(\frac{\mu (\alpha N - \beta - \mu)}{\beta + \mu}\right)$$

Stability
Both
$$-\mu - \frac{\mu (\alpha N - \beta - \mu)}{\beta + \mu} < 0$$
$$(\beta + \mu) \left(\frac{\mu (\alpha N - \beta - \mu)}{\beta + \mu} \right) < 0$$
are true if $\alpha N > \beta + \mu$

Therefore,

$$S^* = \frac{\beta + \mu}{\alpha} \quad , \quad I^* = \frac{\mu \left(\alpha N - \beta - \mu\right)}{\alpha \left(\beta + \mu\right)}$$

is asymptotically stable if $\alpha N < \beta + \mu$

But what about limit cycles?



Bendixson's Negative Criteria

Recall, we need

$$\nabla \cdot (F,G) = \frac{\partial F}{\partial S} + \frac{\partial G}{\partial I}$$

to be of one sign in our region of interest, D. Define D to be all positive values in \Re^2 .



R_0 **Basic reproduction rate**

- R_0 is defined to be the number of secondary infections produced by one primary infection in a wholly susceptible population.
- So if $R_0 > 1$, then the disease will spread.
- For SIR model, R_0 is calculated by linearizing the equation for $\frac{dI}{dt}$ about I = 0, which we have already done.
- So the criteria for determining if the epidemic will spread is, $R_0 \equiv \frac{\alpha N}{\beta + \mu}$.

Conclusions

There are many other applications of differential

- equation models in biology. Once a basic set of
- equations has been developed, there are a
- number of standard techinques used to analyze the stability of the equations.
- We will take time in the lab to explore these and
- other equations.

Acknowledgements

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